# A wearable system to assess walking symmetry in individuals with lower limb impairments

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#### BACKGROUND

- Individuals with lower limb impairments often experience gait asymmetry
- Quantifying asymmetry is important to guide • the focus of rehabilitation

### OBJECTIVE

Develop a wearable system that can:

1. Accurately identify gait events

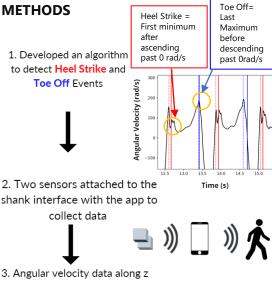




2. Quantify asymmetry in walking 3. Provide real-time data output and biofeedback

through an **android app** 

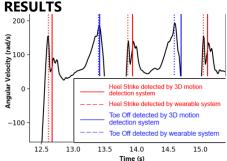
[1]



axis compared to data from 3D motion capture system

A wearable inertial sensor system can be used to analyze walking patterns in real time and provide feedback to improve walking patterns in individuals with lower limb impairments





- Mean timing error for Heel Strikes was 0.5% ± 1.1 and 1.5% ±0.6 for Toe Off detections when tested on offline data from individuals with lower-limb amputations
- Algorithm used these events to calculate stance time, swing time, stance time symmetry and cadence values

#### NEXT STEPS

- Continue testing with user receiving biofeedback
- Continue testing with individuals with lower limb amputations

### **CONCLUSION & RELEVANCE TO BLOORVIEW FAMILIES**

- Reliable detection of gait events allows this system to perform real time analysis of gait symmetry in individuals with lower limb impairments
- Providing **biofeedback guides** the rehabilitation focus
- Additional advantages:





Continue gait training and rehabilitation outside of the hospital User-friendly and portable system promotes consistent usage

## REFERENCES

[1] B. Mariani, S. Rochat, C. J. Büla and K. Aminian, "Heel and Toe Clearance Estimation for Gait Analysis Using Wireless Inertial Sensors," in IEEE Transactions on Biomedical Engineering, vol. 59, no. 11, pp. 3162-3168, Nov. 2012, doi: 10.1109/TBME.2012.2216263.

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